



Mulleruk.

Avinashilingam Institute for Home Science and Higher Education for Women
Deemed to be University Estd.u/s 3 of UGC Act 1956, Category A by MHRD
Re-accredited with 'A++' Grade by NAAC. CGPA 3.65/4, Category I by UGC
Coimbatore-641 043, Tamil Nadu, India

Continuous Internal Assessment Test I – August 2024

Semester - III

Class: II PG

Time: 2Hrs

Major: Mathematics

Max. Marks: 60

23MMAC17 – Advanced Mechanics

Course Outcomes:

- CO1: Identify the static and dynamic characteristics of mechanical systems.
CO2: Analyze different systems in integrals of motion.
CO3: Apply Lagrange's and Hamilton's equations in relevant fields.
CO4: Utilize Hamilton-Jacobi Method in physical science.
CO5: Explore the theory of canonical transformations and its application to dynamical theory.

Part – A 6 x 1 = 6

Circle the correct answer

1. In the presence of constraints, the force component F_i are expressed as functions of _____ .CO1K1
(a) position and time (b) position and velocity
(c) velocity and time (d) position, velocity and time
2. The unilateral or inequality form of constraint is _____ in nature.CO1K2
(a) holonomic (b) non-holonomic
(c) scleronomic (d) rheonomic
3. The virtual work expressions are defined to be _____ in the virtual displacement.
CO2K1
(a) linear (b) quadratic (c) cubic (d) degree n , $n > 3$
4. When the equation of motion of the system is can be expressed as quadratures, then the system is called CO2K2
(a) Holonomic System (b) Rheonomic system
(c) Separable System (d) Orthogonal System

5. The Lagrange's function $L =$ CO3K1
 (a) $T-V$ (b) $V-T$ (c) $T+V$ (d) $2T-V$
6. For natural system, the Jacobi's integral $h =$ CO3K2
 (a) Total energy (b) Kinetic energy
 (c) Potential energy (d) difference of kinetic and potential energy.

Part - B

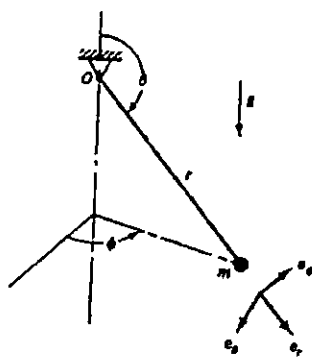
3 x 6 = 18

Answer all questions

7. (a) State and prove principal of virtual work. CO1K3

(or)

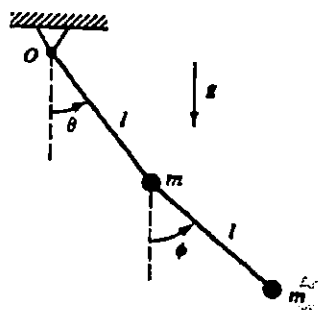
- 7.(b) A particle of mass m is suspended by a massless wire of length $r = a + b \cos \omega t$ ($a > b > 0$) to form a spherical pendulum. Find the equations of motion. CO1K3



8. (a) Explain the equilibrium and stability of a system. CO2K3

(or)

8. (b) A double pendulum consists of two particles suspended by the massless rods, as shown in figure below. Assuming that all motion takes place in a vertical plane. Find the equations of motion. CO2K3



9. (a) State and prove Konig's theorem. (or)

9. (b) Derive Hamilton's equation. CO3K4

Part - C

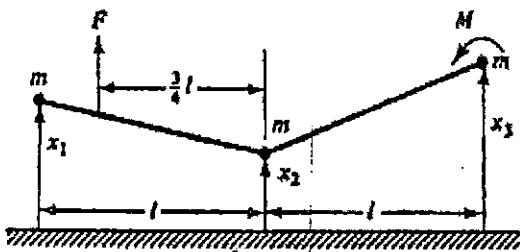
3 x 12 = 36

10. (a) Explain in detail the classification and mathematical description of constraints.

CO1K4

(or)

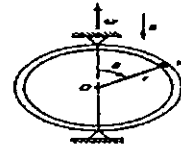
10. (b) Three particles are connected by two rigid rods having a joint between them to form the system as shown. A vertical force F and a moment M are applied as shown. The configuration of the system is given by $x_1 = q_1 + q_2 + \frac{1}{2}q_3$, $x_2 = q_1 - q_2$, $x_3 = q_1 - q_2 + \frac{1}{2}q_3$. Assume small motions. Find the generalized forces Q_1 , Q_2 and Q_3 . **CO1 K4**



11. (a) Derive the standard form of Lagrange's equation for a holonomic system. **CO2K4**

(or)

11.(b) A particle of mass m can slide without friction on the inside of a small tube which is bent in the form of a circle of radius r . The tube rotates about a vertical diameter with a constant angular velocity as shown in figure. Find the differential equation of motion and



Jacobi's integral.

CO2K5

12. (a)(i) Find the stationary values of the function $f=z$, subject to the constraints **CO3K4**

$$\phi_1 = x^2 + y^2 + z^2 - 4 = 0, \phi_2 = xy - 1 = 0$$

(ii) For Brachistochrone problem find a curve $Y(x)$ between the origin and the point (x_1, y_1) such that a particle starting from the rest at O , and sliding down the curve without friction under the influence of a uniform gravitational field, will reach the end of the curve in a minimum time

(or)

(b) Obtain the necessary and sufficient condition for stationary value of the definite integral $I =$

$$\int_{x_0}^{x_1} f[y(x), y'(x), x] dx. \text{CO3K4}$$